

First AMASS External Advisory Board (EAB) Workshop



AMASS

Architecture-driven, Multi-concern and Seamless Assurance and
Certification of Cyber-Physical Systems



Trento, September 11-12, 2017

Agenda (1/3)

The EAB meeting will be held on two different premises:

- ❖ **Day 1, EAB workshop:** Monday, September 11 at FBK:
FBK Scientific and Technological
Hub Via Sommarive, 18 I – 38123 Povo Trento Italy
Phone: (+39) 0461 314 444

- ❖ **Day 2, SASSUR workshop:** Tuesday, September 12 at the
SafeComp venue:
Grand Hotel Trento
Piazza Dante, 20 - 38122 Trento Italy
Phone: (+39) 0461 271000

Agenda (2/3): Monday, September 11 (FBK premises)

Start	End	Description	Speaker
9:00	9:30	Project Outline	Huáscar Espinoza
9:30	10:00	Technical Overview	Barbara Gallina
10:00	10:30	Selected Case Studies	Benito Caracuel, Helmut Martin and Thierry Lecomte
10:30	11:00	Coffee break	
11:00	11:50	Project Outreach and Community Building	Ran Bi and Gaël Blondelle
11:50	12:20	Intra and Cross-Domain Reuse	Barbara Gallina
12:30	13:30	Lunch	
13:30	14:00	Architecture-Driven Assurance	Stefano Puri
14:00	14:30	Multi-concern Assurance	Thomas Gruber
14:30	15:00	Seamless Interoperability	José de la Vara
15.00	16:30	EAB Feedback Brainstorming	Moderated by Gaël Blondelle, Huáscar Espinoza and Barbara Gallina.
16.30	17:00	Coffee break	
17:00	17.30	Wrap-up	Moderated by Gaël Blondelle, Huáscar Espinoza and Barbara Gallina

Agenda (3/3): Tuesday, Sept 12 (SASSUR workshop)

Start	End	Description	Authors
8:00	9:00	Registration	
9:00	9:05	Welcome	Alejandra Ruiz / Jose Luis de la Vara/ Tim Kelly
9:05	9:55	Keynote: Developing metrics for compliance using the RTCA DO-178C at Embraer.	Johnny Marques - Embraer
9:55	10:25	Representation of Safety Standards with Semantic Technologies Used in Industrial Environments	Jose Luis de La Vara, Álvaro Gómez, Elena Gallego, Gonzalo Génova and Anabel Fraga
10:25	11:00	Coffee break	
11:00	11:30	Automotive SPICE, Safety and Cybersecurity Integration	Georg Macher, Alexander Much, Andreas Riel, Richard Messnarz and Christian Kreiner
11:30	12:00	Safety and Security Co-Engineering and Argumentation Framework	Helmut Martin, Robert Bramberger, Christoph Schmittner, Zhendong Ma, Thomas Gruber, Alejandra Ruiz and Georg Macher
12:00	12:30	Process Assessment in Supplier Selection for Safety-Critical Systems in Nuclear Domain	Timo Varkoi and Risto Nevalainen
12:30	13:30	Lunch	
13:30	14:00	A Runtime Risk Assessment Concept for Safe Reconfiguration in Open Adaptive Systems	Nikita Bhardwaj and Peter Liggesmeyer
14:00	14:30	Assuring Degradation Cascades of Car Platoons via Contracts	Irfan Slijivo, Barbara Gallina and Bernhard Kaiser
14:30	15:30	Industrial panel	



AMASS

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Project Overview

First EAB Workshop
Trento, Sept 11, 2017

Huáscar Espinoza, Ph.D.
AMASS Project Manager



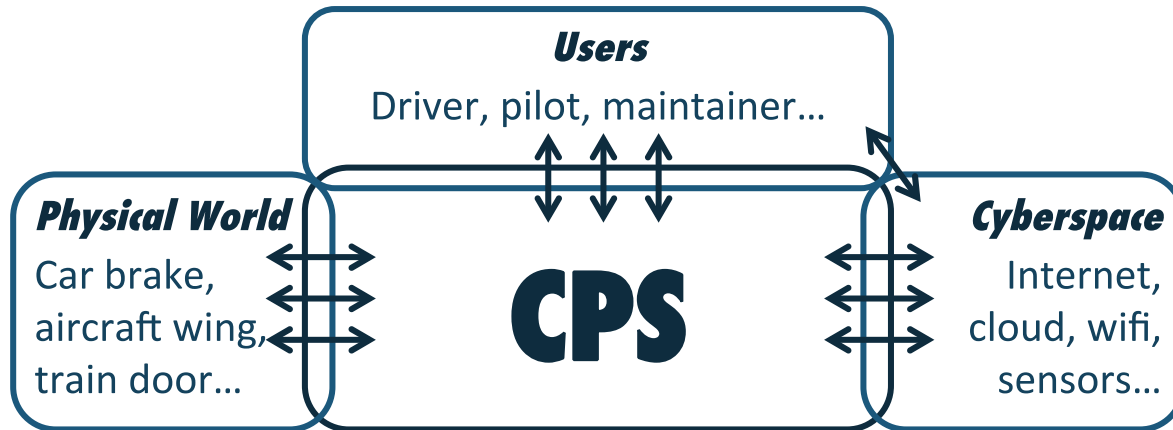
AMASS in a Nutshell



- ❖ **20,5** Million € Total budget
- ❖ **2500** Person-Months Effort
- ❖ **36** Months Duration (04/16-03/19)
- ❖ **29** Partners
- ❖ **8** Countries
- ❖ **16** Advisory Board Members

No	Participant organisation name	Short	Country
1	Tecnalia Research & Innovation	TEC	ES
2	Honeywell Internacional	HON	CZ
3	Schneider Electric Spain	TLV	ES
4	ANSYS medini Technologies AG	KMT	DE
5	Mälardalen University	MDH	SE
6	Eclipse Foundation Europe	ECL	DE
7	Infineon Technologies	IFX	DE
8	AIT Austrian Institute of Technology GmbH	AIT	AT
9	Fondazione Bruno Kessler	FBK	IT
10	Intecs	INT	IT
11	Assystem Germany GmbH	B&M	DE
12	GMV Aerospace and Defence, S.A.U.	GMV	ES
13	RINA Services	RIN	IT
14	Thales Alenia Space España	TAS	ES
15	Universidad Carlos III de Madrid	UC3	ES
16	Rapita Systems	RPT	UK
17	Knowledge Centric Solutions	TRC	ES
18	OHB Sweden AB	OHB	SE
19	Masaryk University	UOM	CZ
20	Alstom Transport	ALS	FR
21	Kompetenzzentrum – Das virtuelle Fahrzeug Forschungsgesellschaft mbH	VIF	AT
22	Alliance pour les technologies de l' Informatique	A4T	FR
23	COMMISSARIAT A L'ENERGIE ATOMIQUE ET AUX ENERGIES ALTERNATIVES	CEA	FR
24	CLEARSY SAS	CLS	FR
25	ALTEN SVERIGE AKTIEBOLAG	ALT	SE
26	Lange Research Aircraft GmbH	LAN	DE
27	Thales Italia SpA	THI	IT
28	RISE Research Institutes of Sweden	SPS	SE
29	Comentor AB	COM	SE

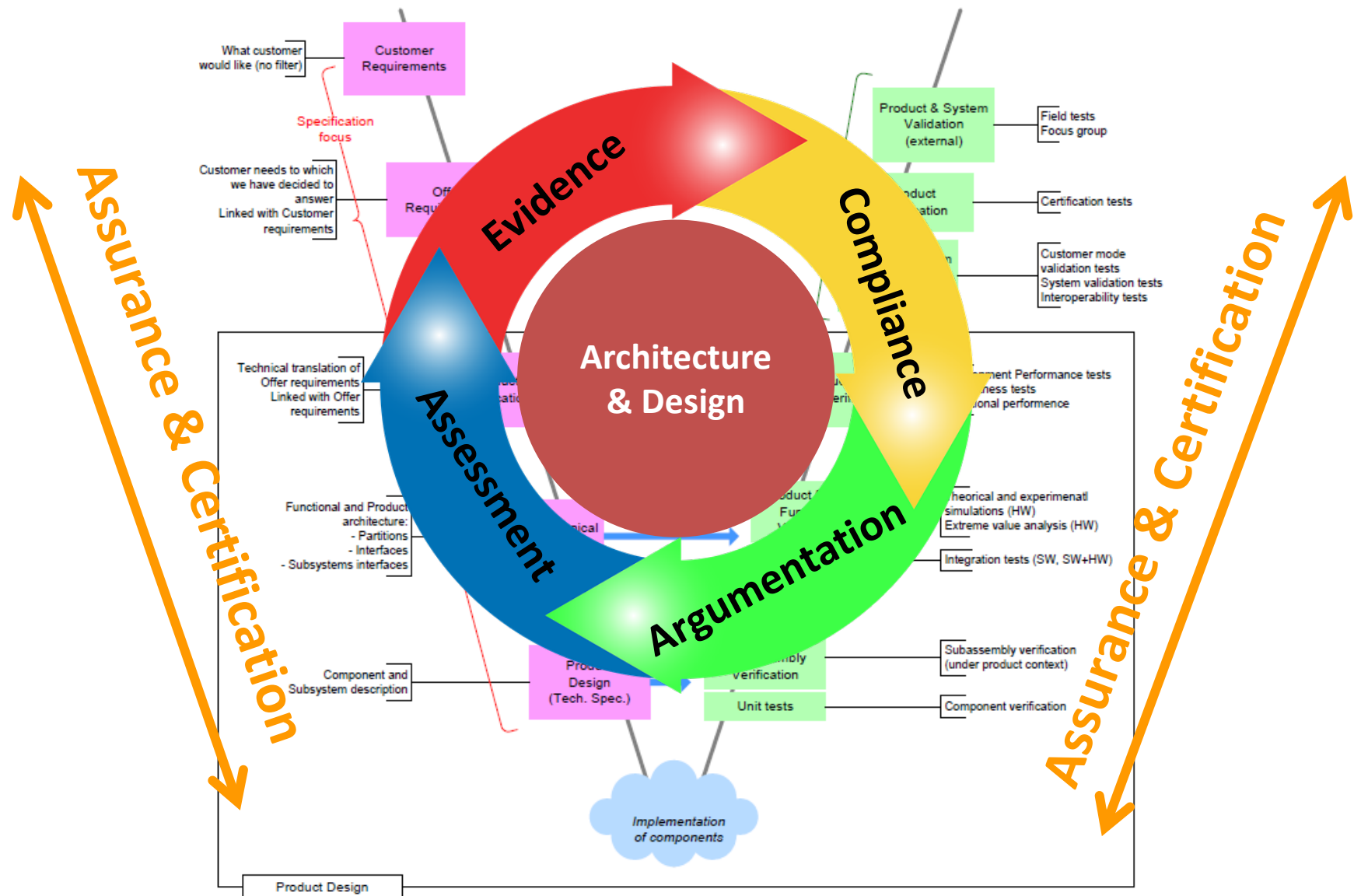
AMASS Motivation: The Problem



- ❖ Increase in product **complexity**
- ❖ Very **high costs & effort**
- ❖ Lack of **standardized & harmonized practices**
- ❖ New assurance & certification **risks**
- ❖ **Architecture-specific assurance needs**
- ❖ Need for addressing **multiple dependability concerns**
- ❖ Wider **variety of tools and stakeholders**
- ❖ Insufficient **reuse support**



Scope of Assurance & Certification in AMASS



AMASS Motivation: The Target Solution

Project Goals

Holistic approach and tool support for

Architecture-driven, Multi-concern, Seamless, Reuse-Oriented Assurance & Certification

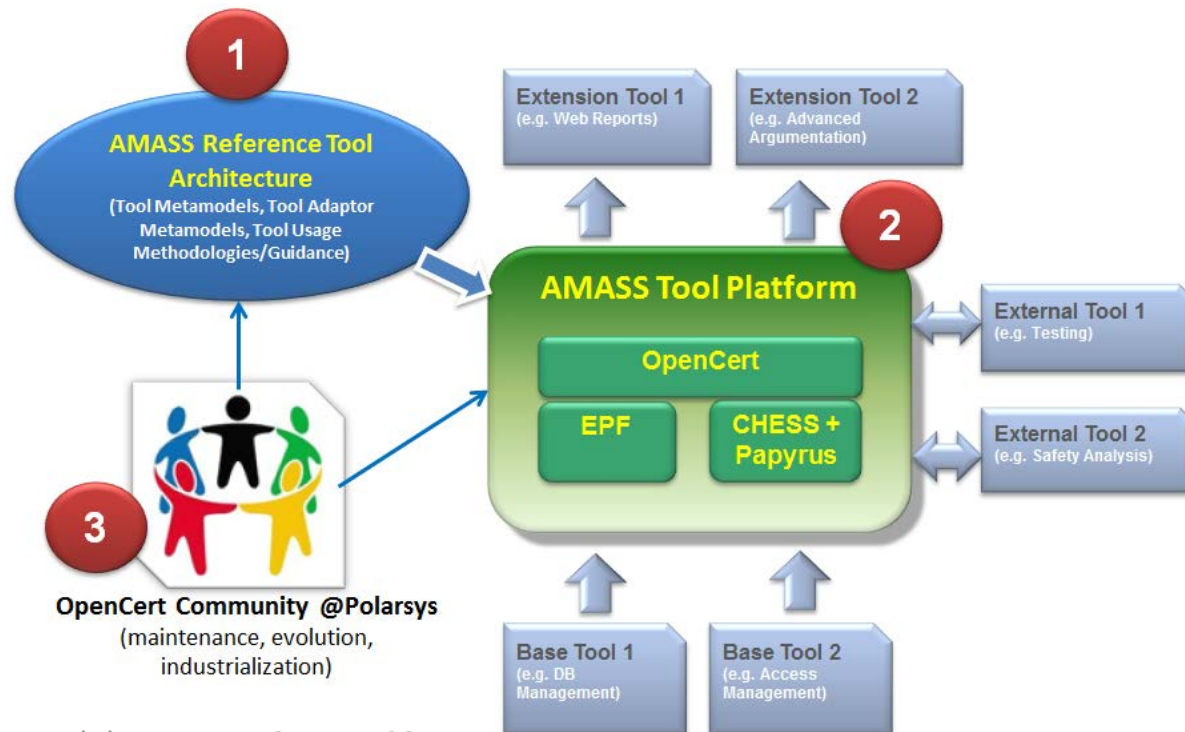
Effort reduction → Higher design efficiency

Reuse cost reduction → Lower recurring costs

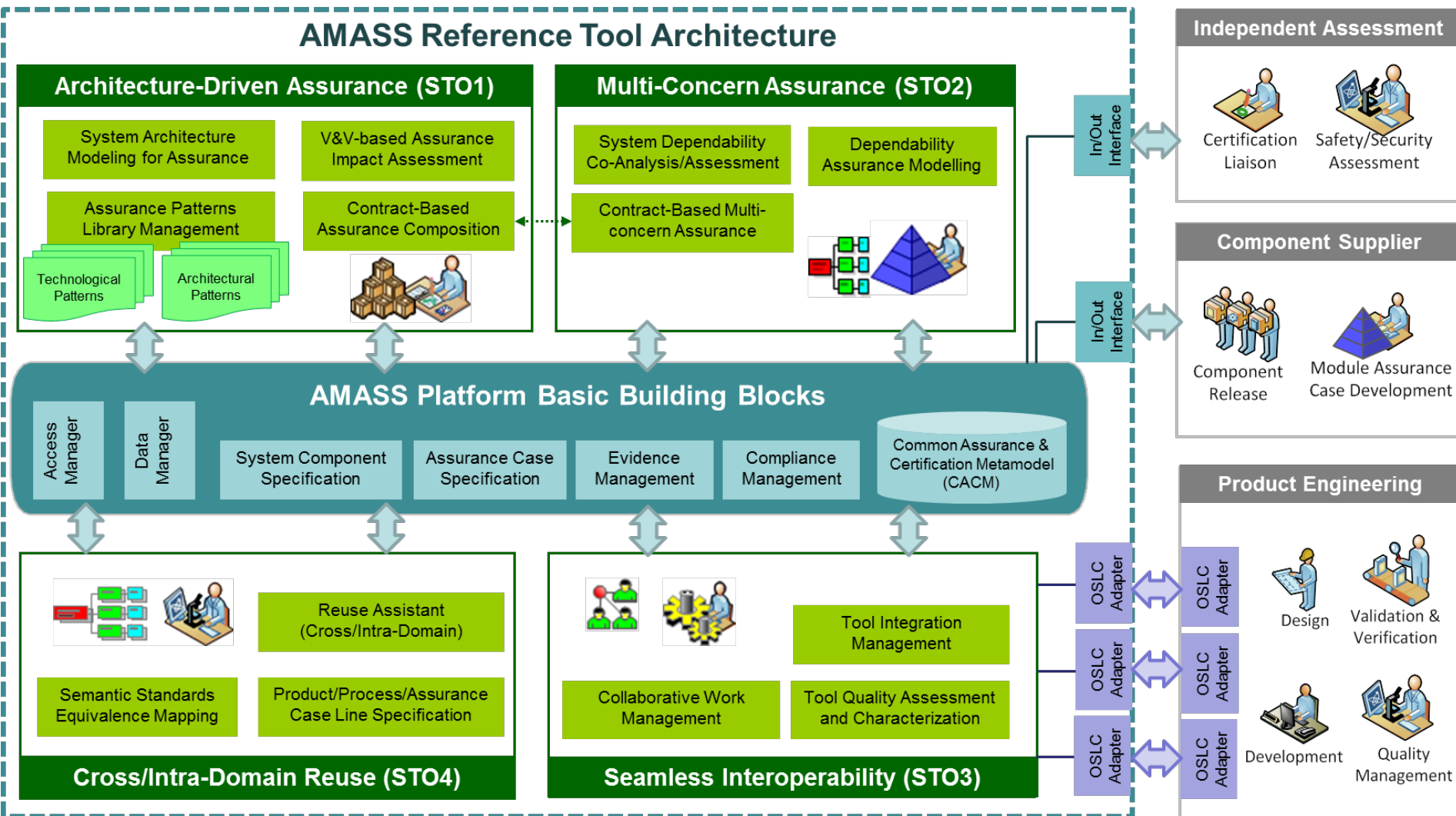
Assurance risks reduction → Easier innovation

Harmonization increase → Openness & interoperability

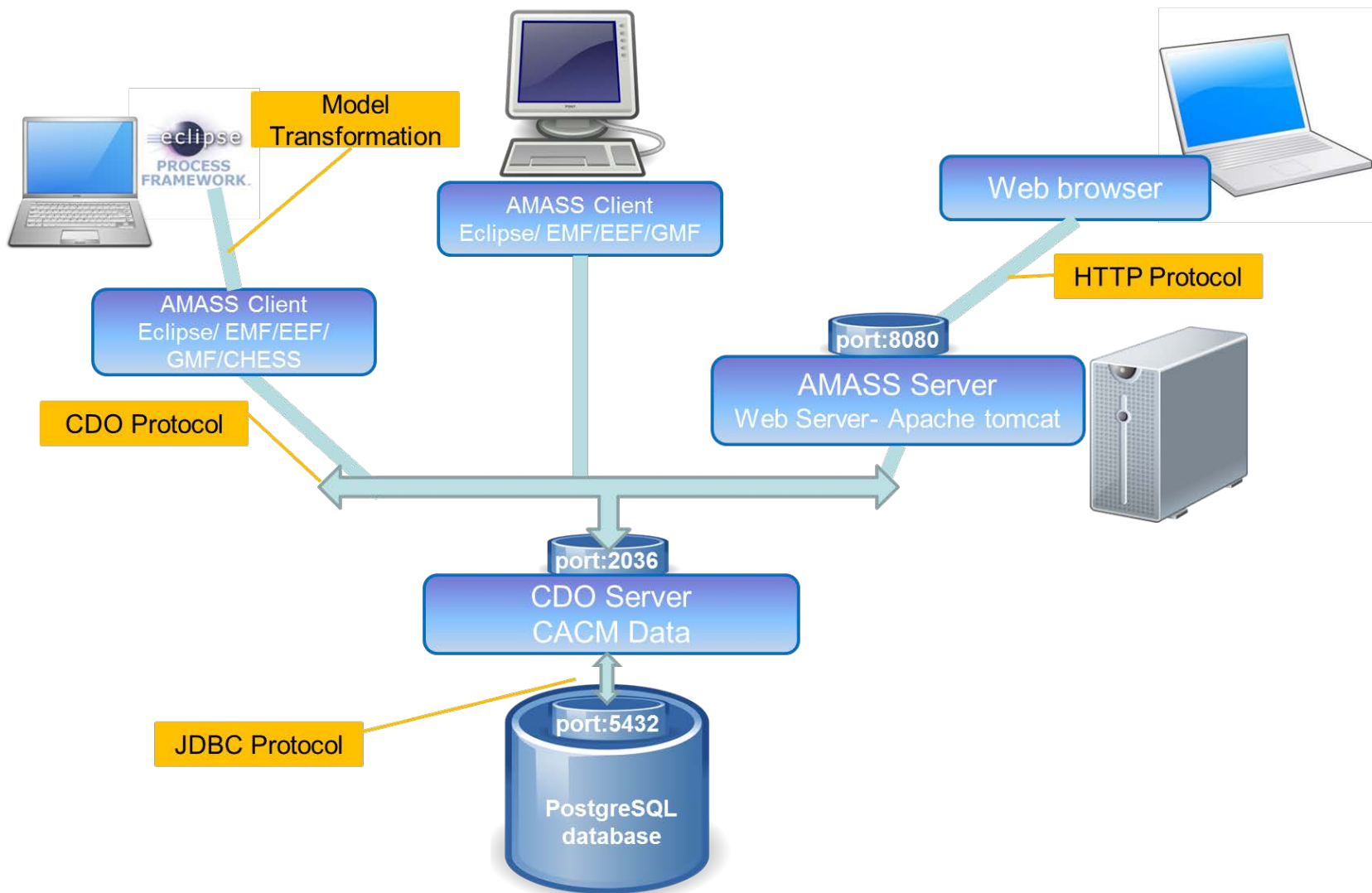
Tangible Results



AMASS Reference Tool Architecture

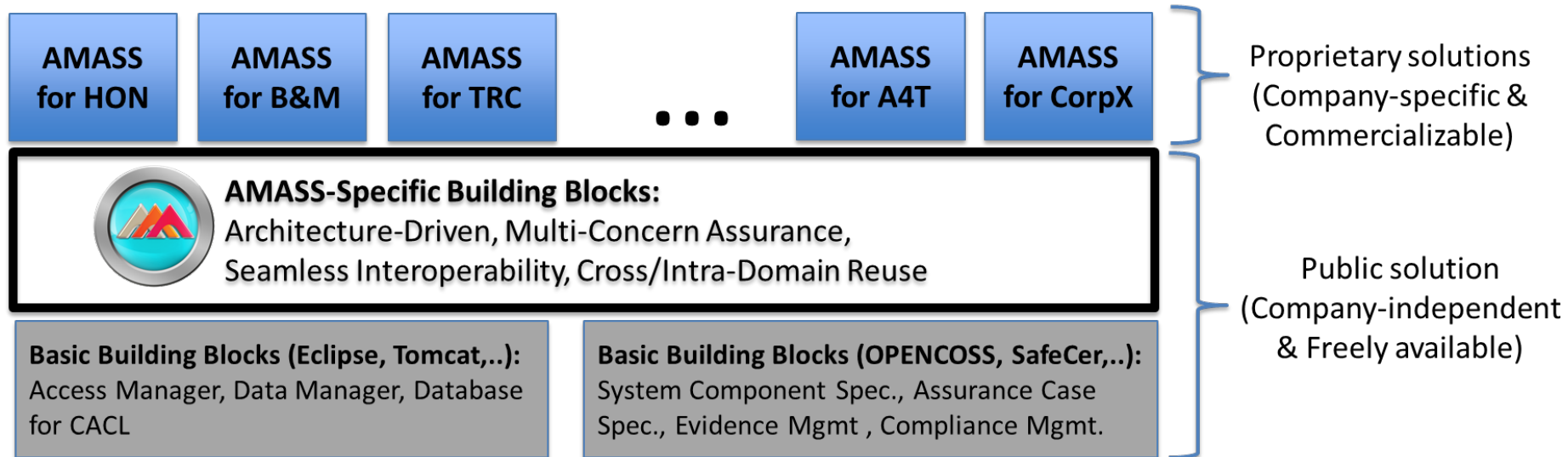
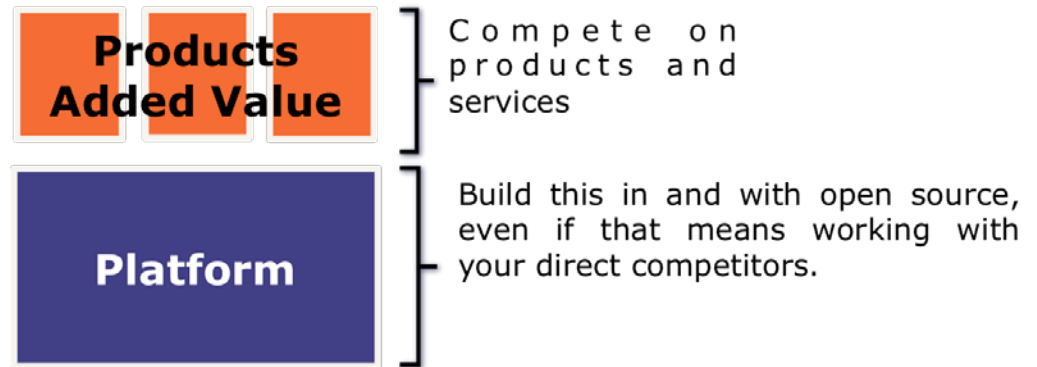


AMASS Tool Platform

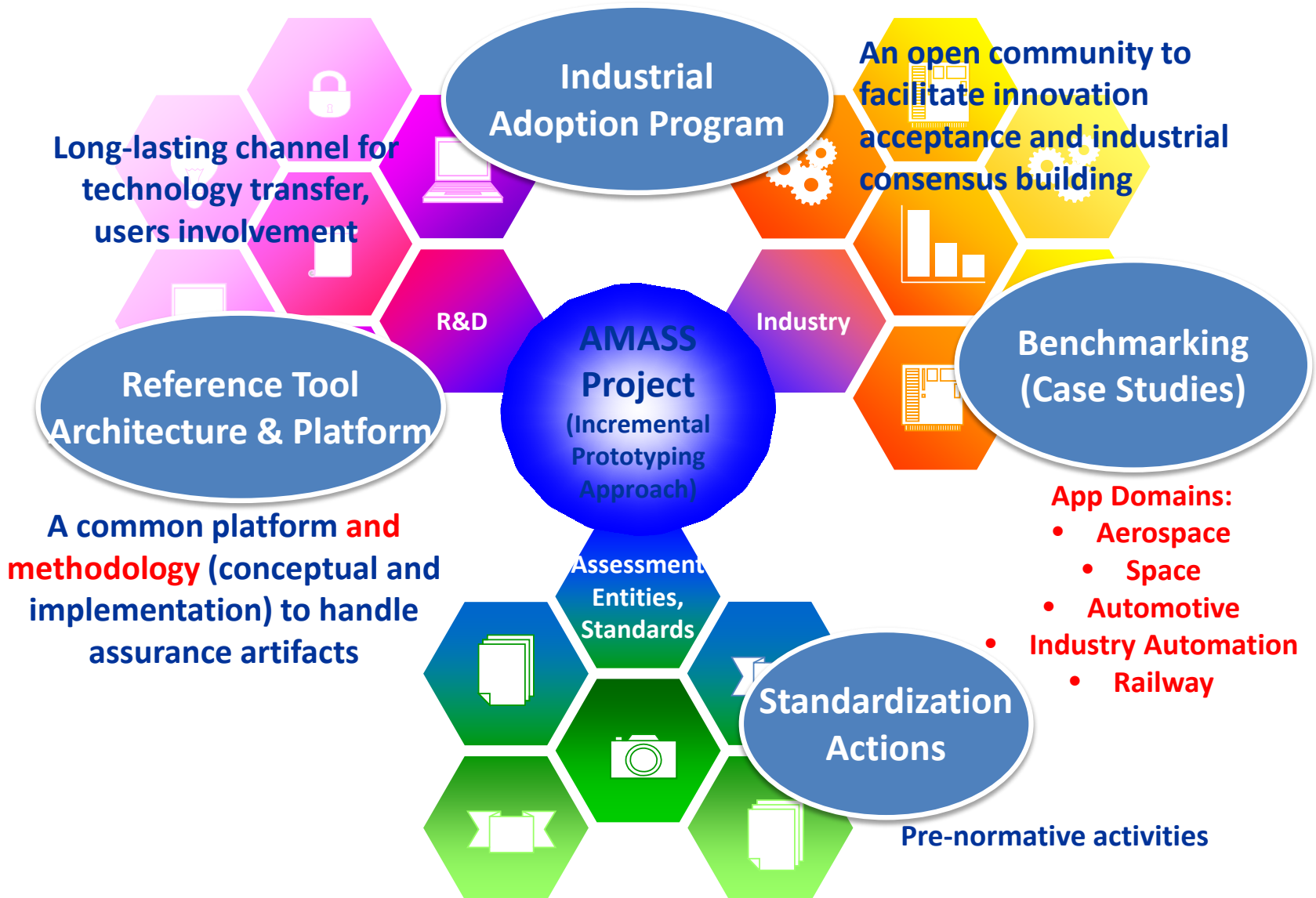


AMASS Open Community

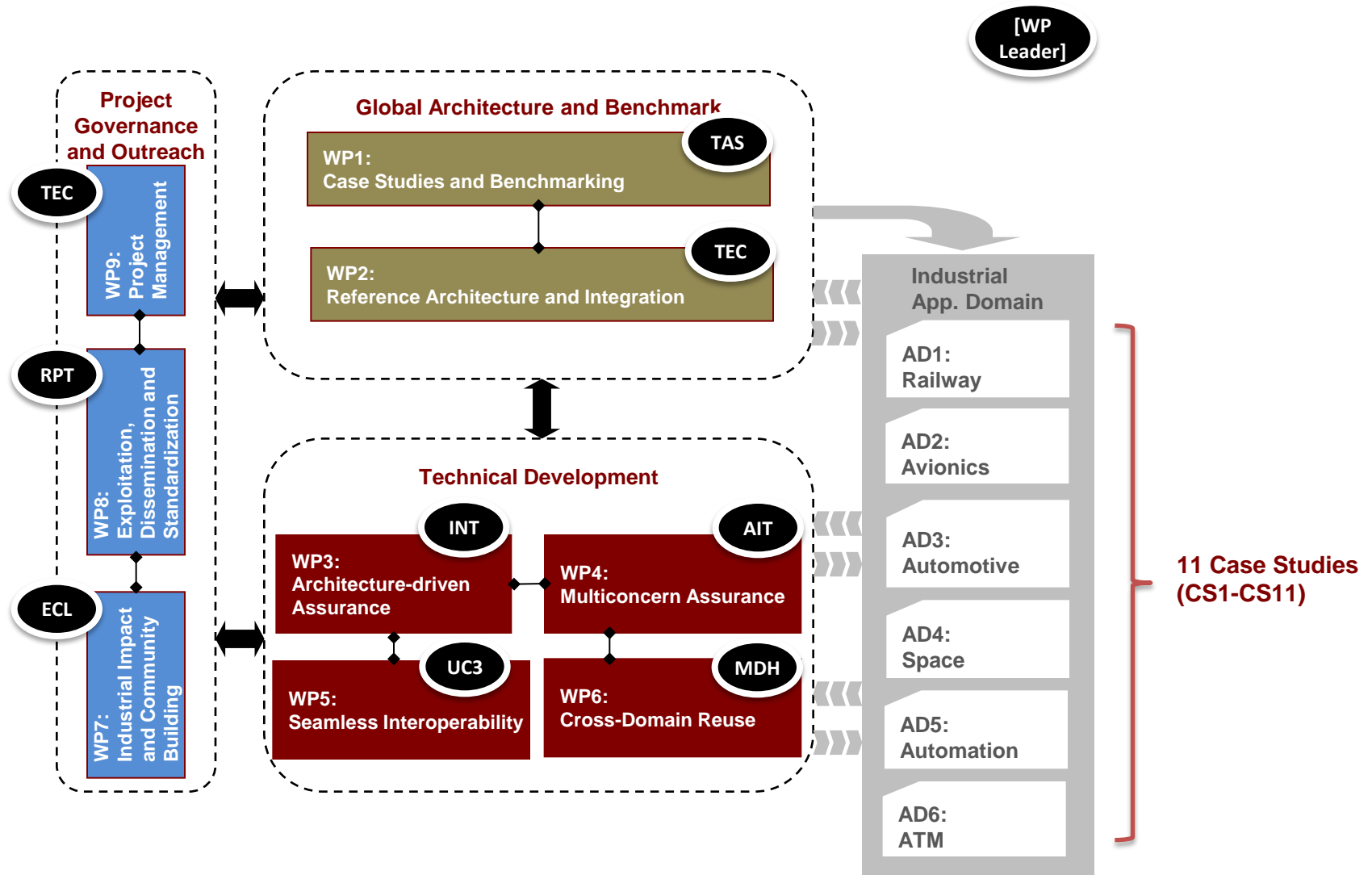
Eclipse Open-Source Model



AMASS Overall Strategy



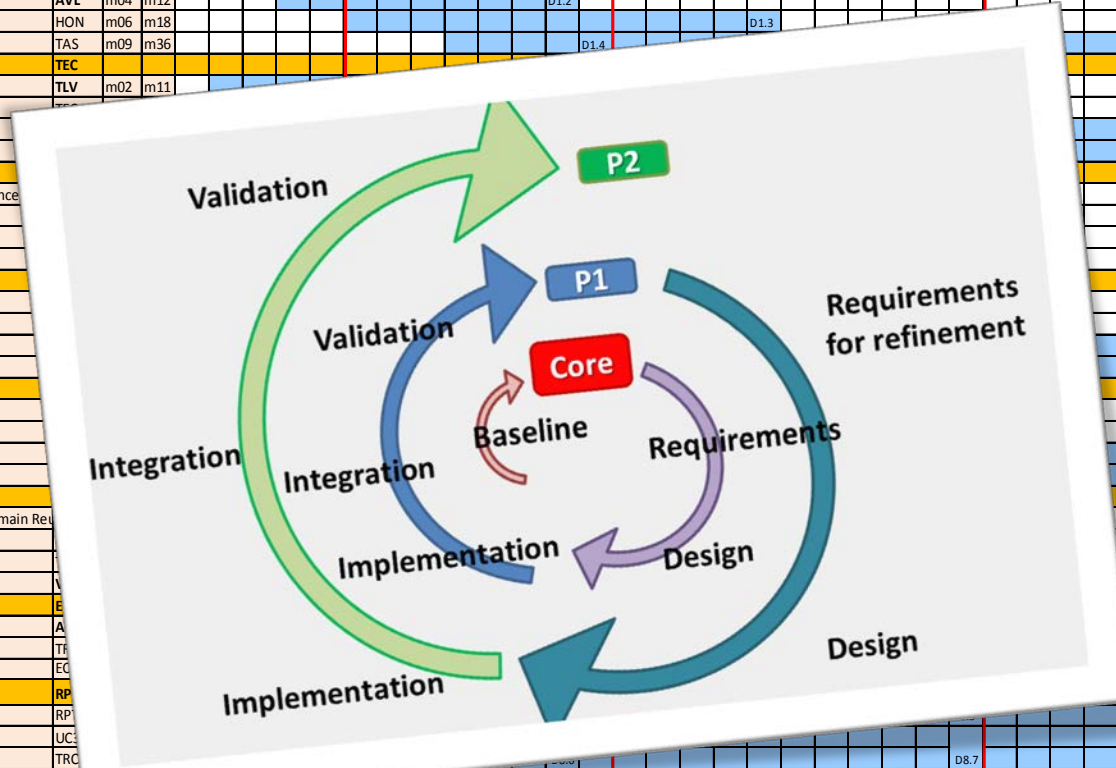
Project Work Package (WP) Structure



AMASS Industrial Case Studies

CS1: <u>Industrial Automation domain</u>	Industrial and Automation Control Systems (IACS)
CS2: <u>Automotive domain</u>	Advanced driver assistance function with electric vehicle sub-system
CS3: <u>Automotive domain</u>	Collaborative automated fleet of vehicles
CS4: <u>Space domain</u>	Design and safety assessment of on-board software applications in Space Systems
CS5: <u>Railway domain</u>	Platform Screen Doors Controller
CS6: <u>Railway domain</u>	Automatic Train Control Formal Verification
CS7: <u>Avionics domain</u>	Safety assessment of multi-modal interactions in cockpits
CS8: <u>Automotive domain</u>	Telematics function
CS9: <u>Air Traffic Management domain</u>	Safety-Critical SW Lifecycle of a Monitoring Syst. for NavAid
CS10: <u>Space domain</u>	Certification basis to boost the usage of MPSoC architectures in the Space Market
CS11: <u>Space domain</u>	Design and efficiency assessment of model based Attitude and Orbit Control software development

Project Schedule

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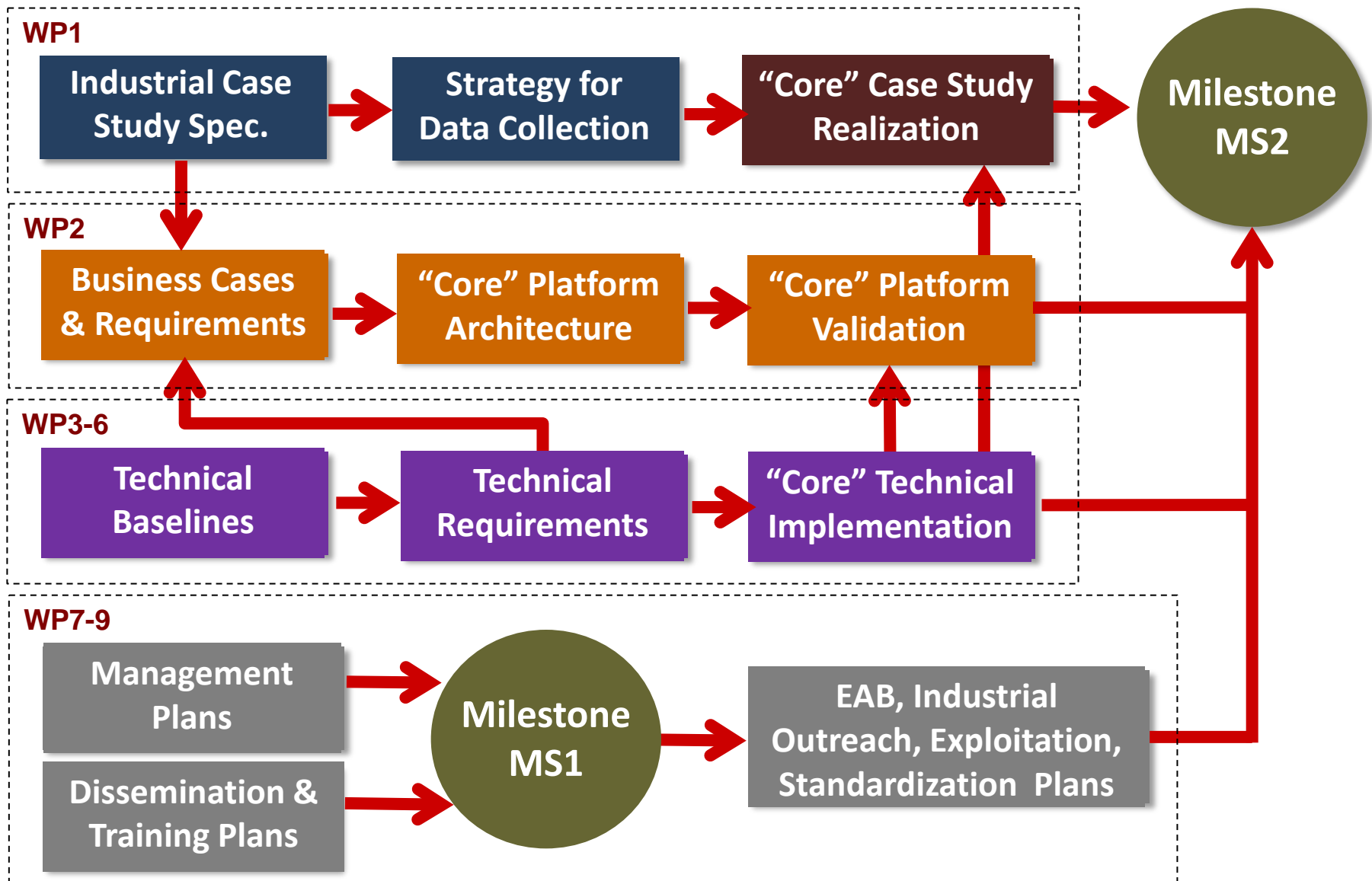
M1
Project Inception

**First Prototype:
Core AMASS Platform
Validated in Laboratory**

M3
Second Prototype:
Full AMASS Platform
Validated in Laboratory

M4
Final Prototype:
Full AMASS Platform Validated
in Relevant Environment

Activities and Milestones during First Year



Results during First Year

❖ Open Deliverables available at:

<http://www.amass-ecsel.eu/content/deliverables>

❖ First Prototype, Eclipse/Polarsys OpenCert website:

<https://polarsys.org/opencert/>

❖ Dissemination Material:

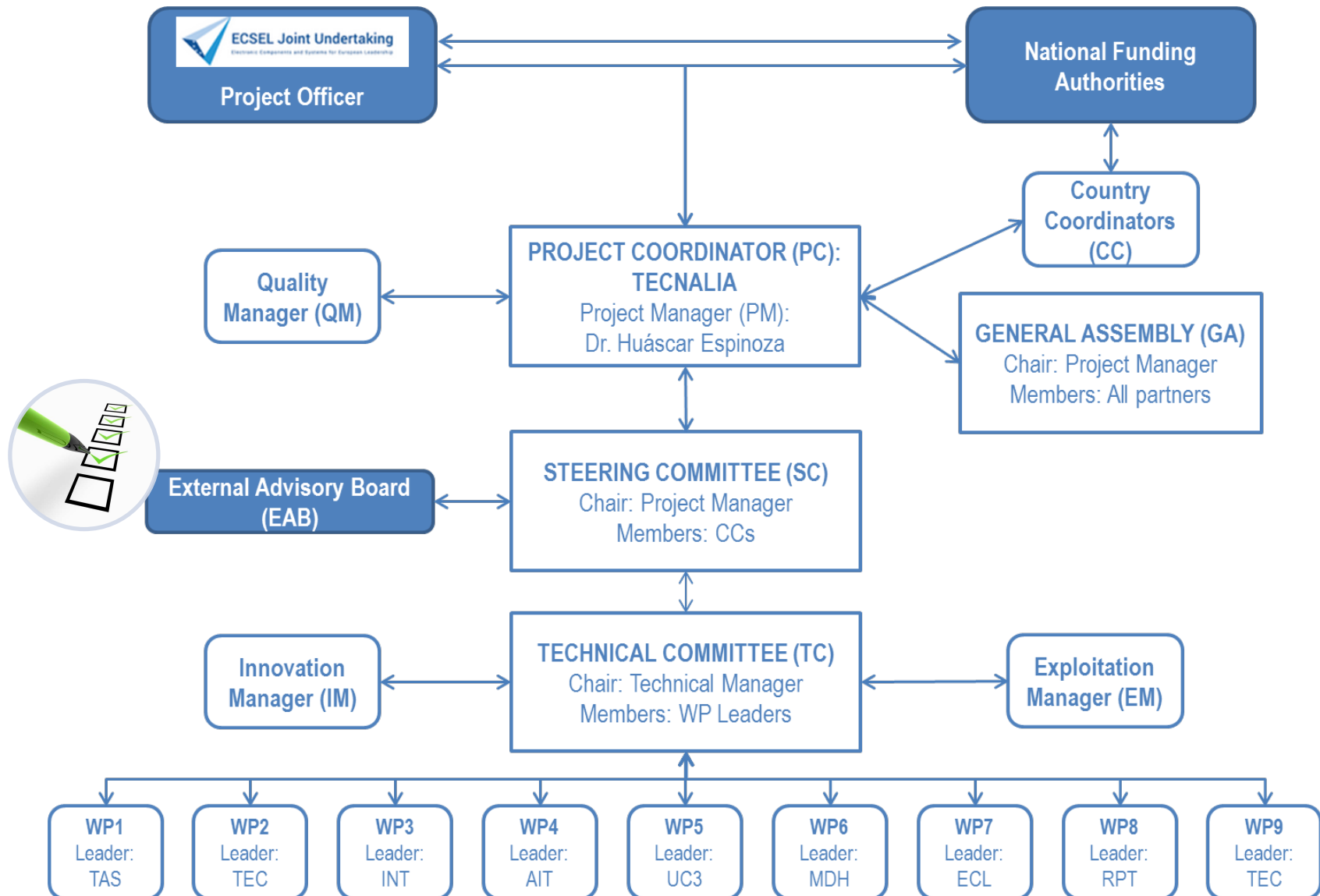
<http://www.amass-ecsel.eu/content/dissemination>

❖ Publications:

<http://www.amass-ecsel.eu/content/publications>

EAB Management

Project Management Structure



EAB Members Role



- ❖ Review the project outcomes and identify its strong/weak points with respect to the objectives of the project and the application of its results.
- ❖ Provide unbiased insights and feedback from a third party point-of-view, because they are not involved in the project execution and the day-to-day business in the project.
- ❖ Comment and guide on the consortium' skills and the relevance of their proposals and actions.
- ❖ Promote the exposure of AMASS activities in industry.

EAB Coordinator Role



EABC role assigned to Huáscar Espinoza (TEC) and Gael Blondelle (ECL)

- ❖ Updating frequently the progress of work, keeping alive on-going discussion.
- ❖ Organization of the EAB events (meetings, workshops, forums, etc.), including logistics.
- ❖ Collection of advice, comments and recommendations from the EAB members.
- ❖ Dissemination of information to EAB members.
- ❖ Reporting of EAB discussions (summary and recommendation from the EAB).



EAB Members

Name	Surname	Potential Partner	Country
George	Romanski	Pending (New job in FAA)	US
Antonio	Priore	Ultra Electronics CONTROLS	UK
Javier	Ibanez-Guzman	Renault	France
Miren	Illarramendi	University of Mondragon	Spain
Tim	Kelly	U. York	UK
Mattias	Nyberg	Scania	Sweden
Johnny	Marques	Embraer	Brasil
Anders	Sandin	LFV	Sweden
Laurent	Fabre	Critical System Labs (CSL)	Canada
Ganesh	Pai	NASA	USA
Markus	Wallmyr	CrossControl AB	Sweden
Timo	Varkoi	Spinet	Finland
Marion	Lepmets	SoftComply	Estonia
Kurt	Tschabuschnig	MAGNA STEYR Engineering AG & Co KG	Austria
Pascual	Breton Taratiel	CAF	Spain
Raquel	Arriba		

Thank you for your attention!

